

# Locating coalescing singular values of large two-parameter matrices

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Available online 21 October 2010

## Abstract

Consider a matrix valued function  $A(x) \in \mathbb{R}^{m \times n}$ ,  $m \geq n$ , smoothly depending on parameters  $x \in \Omega \subset \mathbb{R}^2$ , where  $\Omega$  is simply connected and bounded. We consider a technique to locate parameter values where some of the  $q$  dominant ( $q \leq n$ ) singular values of  $A$  coalesce, in the specific case when  $A$  is large and  $m > n \gg q$ .

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MSC: 15A18; 15A23; 65F15; 65F99; 65P30

Keywords: Coalescing singular values; Two-parameter functions; Sparse matrices

**Notation.** An  $m \times n$  real matrix is indicated with  $A \in \mathbb{R}^{m \times n}$ . We always consider the 2-norm for vectors and matrices. A matrix valued function  $A: \mathbb{R} \rightarrow \mathbb{R}^{m \times n}$ , continuous with its first  $l$  derivatives ( $l \geq 0$ ), is indicated as  $A \in \mathcal{C}^l(\mathbb{R}, \mathbb{R}^{m \times n})$ . If  $l=0$ , we also simply write  $A \in \mathcal{C}$ . If  $A \in \mathcal{C}^l(\mathbb{R}, \mathbb{R}^{m \times n})$  is periodic of (minimal) period  $\tau > 0$ , we write it as  $A \in \mathcal{C}_\tau^l(\mathbb{R}, \mathbb{R}^{m \times n})$ . With  $\Omega \subset \mathbb{R}^2$  we indicate an open and bounded simply connected planar region, and  $x = (x_1, x_2)$  will be coordinates in  $\Omega$ . For a function  $A(x)$ ,  $x \in \Omega$ , we will write  $A \in \mathcal{C}^l(\Omega, \mathbb{R}^{m \times n})$  as appropriate.

## 1. Introduction

Consider a matrix  $A \in \mathbb{R}^{m \times n}$ ,  $m \geq n$ . Recall that the – reduced – SVD (Singular Value Decomposition) of  $A$  is the decomposition

$$A = U \Sigma V^T,$$

where  $U \in \mathbb{R}^{m \times n}$  is orthonormal ( $U^T U = I_n$ ),  $V \in \mathbb{R}^{n \times n}$  is orthogonal, and  $\Sigma \in \mathbb{R}^{n \times n}$  is the diagonal matrix of the singular values:  $\Sigma = \text{diag}(\sigma_1, \dots, \sigma_n)$ ,  $\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_n \geq 0$ . The SVD of a matrix is one of the most useful decompositions in linear algebra: the rank of  $A$ , as well as orthogonal representations for fundamental subspaces associated with  $A$  can be nicely retrieved from the factors of the SVD; see [5].

An important application of the SVD is that it is easy to obtain from it the best approximation (in the 2-norm) to the matrix  $A$  among matrices of a given rank. Namely, if  $A = U \Sigma V^T$ , and  $\sigma_1 \geq \dots \geq \sigma_q > \sigma_{q+1} \geq \dots \geq \sigma_n$ , then the best approximation of rank  $q$  to  $A$  is given by  $U^{(q)} \Sigma^{(q)} (V^{(q)})^T$ , where  $U^{(q)} = U(:, 1:q)$ ,  $V^{(q)} = V(:, 1:q)$  and

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